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EUM/FLO/VWG/19/1086621, v1 Draft, 23 May 2019

### **Presentation summary**

## EUMETSAT brief overview

- . Who we are
- · What we do

## Orekit use at EUMETSAT

- Station Keeping Analysis
- Station Keeping North South optimisation
- Integration with Matlab
- Orbit analysis/comparisons (mean elements)
- Metop End-Of-Life Disposal
- Radio Occultation
- Space Situational Awareness

#### **EUMETSAT** – who we are

EUropean organisation for the exploitation of METeorogical SATellites

Intergovernmental organisation with 30 Member States

Member States have full access to data and services



### EUMETSAT – what we do

EUMETSAT operates a fleet of satellites in geostationary and polar orbit, which provide a wide array of Earth observation data for weather, climate and environmental monitoring

Flying satellites:

- Low Earth Orbit (LEO)
   Metop, Sentinel, Jason
- Geosynchronous Earth Orbit (GEO) Meteosat Second generation

Future programmes – EPS-SG, Jason-CS (LEO) – MTG (GEO)



#### **Current EUMETSAT satellites**

#### METOP-A, -B, -C (98.7° incl.)

LOW EARTH, SUN-SYNCHRONOUS

EUMETSAT Polar System (EPS) / INITIAL JOINT POLAR SYSTEM

#### SENTINEL-3 (98.65° incl.)

LOW EARTH, SUN-SYNCHRONOUS COPERNICUS satellites delivering Marine and Land Observations

#### JASON-2 & -3 (63° incl.)

LOW EARTH, non-SYNCHRONOUS

Ocean Surface Topography mission, shared with CNES/NOAA/EU

#### **METEOSAT-8**

GEOSYNCHRONOUS Meteosat 2nd generation providing IODC, 41.5°E

#### METEOSAT-9, -10, -11

GEOSYNCHRONOUS

Meteosat 2nd generation

#### **Two-satellite system**

Full disc imagery mission (15 mins): Meteosat-11 (0°) Rapid scan service over Europe (5 mins): Meteosat-10 (9.5° E) Meteosat-9 in orbit backup at 3.5° E

# **Meteosat spacecrafts**

**EUMETSAT** geosynchronous satellites for weather forecast and climate-change monitoring



Meteosat First Generation (MFG )...till 2017





#### Meteosat Second Generation (MSG), current

- 2 services
- 4 satellites, spin-stabilized (~100 rpm)
- Orbit Determination (OD): S-band ranging measurements from 2 stations per satellite (with swaps)

Meteosat Third Generation (MTG)...from 2021





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# Station Keeping Analysis Tool (SKAT)



## Station Keeping Analysis Tool (SKAT)

- OPERABILITY: Realistic evaluation of orbit maintenance strategies in LEO&GEO missions, simulated over long time spans
- End-to-end, full-chain of orbit determination and control, simulated with uncertainties and automated control rules 'in-the-loop'



See ISSFD23 FDOP1-2 Paper: High Fidelity End-to-End orbit control simulations at EUMETSAT

## Station Keeping Analysis Tool (SKAT), controls

- Cross coupling , orbit determination and manoeuvre realisation error (deterministic or stochastic) , eclipse constraints are simulated.
- Monte Carlo option

#### Different 'Controls' implemented

- LEO controls ----->
- Mean Local Solar Time
- In Plane Ground Track Grid
- Out-Of-Plane Ground Track Grid

GEO controls -----> example next slide

- Inclination (inclination vector circle)
- Longitude (parabolic longitude)
- Eccentricity (eccentricity circle; single or double burn type)
- Satellites Co-locations schemes



## Station Keeping Analysis Tool (SKAT) Example, 2xMTGs co-location by e-i separation



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# Station Keeping Optimisation of North South (SKONS)

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# Station Keeping Optimisation of North South (SKONS) Simulation principle

- PROPELLANT OPTIMISATION: Realistic evaluation of orbit long term control for mission analysis and eventual mission extensions studies for GEO (further sophistication with respect to SKAT)
- GEO inclination control problem is driven by J2 and Sun/Moon effects orbital plane precession around a stable configuration (Laplace plane)
- North/South Manoeuvre execution can take advantage of reduced natural drift within wide inclination control dead-band  $i(i_x, i_y) = (i \sin \Omega, -i \cos \Omega)$  (2)



### Station Keeping Optimisation of North South (SKONS) LEOP+SK optimisation for GEO



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## Station Keeping Optimisation of North South (SKONS) Software design

#### Four-stages optimisation:

- 1) Initialisation & setup of BOL orbits and *PropagatorFactory* (DSST or numerical)
- 2) Manoeuvre free BOL period towards the Routine inclination control circle, till 1st exit violation (*EventDetector*) and computation of 1st manoeuvre
- 3) Routine phase sequence of NS: optimal direction for manoeuvres to move the inclination vector in control circle with approximate orbit pole drift model
- 4) Manoeuvre free EOL period, with adjustment of last routine manoeuvre to reach the target EOL inclination

#### Various constraints applied in the optimisation:

- manoeuvre-free periods every year(eclipse)
- minimal duration between NS manoeuvres
- days in the week for manoeuvre execution

#### JAVA 8 environment+3 open-source libraries:

- OREKIT-9.2, for flight dynamics
- HIPPARCHUS-1.3, for mathematics
- JFreeChart, for plotting



# **Integration with Matlab**



#### Integration with Matlab

- Matlab offers many advantages (with the drawback you need a license)
- Rapid prototyping, access to powerful toolboxes and graphics
- Orbit propagation and orbital events detection (including attitude laws) for multi-mission multi-purpose analysis

Example: Jason-2 and Jason-3 'interleave' orbits (one-day tracks)



## Integration with Matlab

• Revisiting and coverage (with equispaced Earth grid)





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### Integration with Matlab

 Direct Broadcast antenna coverage for given instrument swath





AOI = Area Of Interest (longitudes -65 to 50 deg, latitudes 30 to 80 deg north)



Observations over DBA coverage: 29.0000 days (412 orbits)



412 orbits. Total Observations

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# **Orbit Analysis/Comparison**



#### **Orbit Analysis/Comparison. Mean elements (1/2)**

- Mean elements analysis
  - supported by Orekit/DSST
  - or by simply integral average over integer number of orbits
  - Semi-major axis mean elements show 'manoeuvres' out of the much larger orbital variations (Sentinel-3 example, 1000 times more)



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#### **Orbit Analysis/Comparison. Mean elements (2/2)**

#### Mean eccentricity vector evolution

- Full earth 'cycle' (or subcycle) to be averaged to obtained mean eccentricity
- 100 times smaller variation that osculating orbital values
- 4-month rotation around theoretical frozen eccentricity value (with additional up/down seasonal movement due to solar radiation pressure)
- Manoeuvres planned looking at 'mean evolution' to guarantee frozen conditions







## **Other tools**



#### Metop End-Of-Life Disposal.

- Metop-A to be disposed, complying with ECSS and ISO standards:
  - 25 year decay orbit to be reached via de-orbiting manoeuvres, followed by s/c passivation
- Orekit implementation for planning manoeuvre sequence(s)
- Monitoring fuel on-board and fulfilling constraints:
  - · last burns in combined GS visibility (implying perigee targeting),
  - minimum geodetic altitude to be respected (AOCS constraints),
  - freeing operational orbit (additional safety rules)...
  - Developed in Matlab (calling Orekit), then moved to Python



#### **Radio Occultations (JOccultations)**

Technique to measure physical properties of atmosphere, with radio signals by navigation satellites (GPS, etc)

- Sounding powerful and inexpensive
- NWP (Numerical Weather Prediction) and Climate

JOccultations: tool for predicting radio-occultation events between multiple LEO satellites (primary objects) and multiple GNSS satellites (secondary objects), e.g. GPS, GALILEO, GLONASS, Beidou



nlanet

#### **Space situational awareness**

- . JFilterTLE
  - filters from TLE catalogues
- **JCloseAp** •

The minimum approach is defined mathematically as the epoch when:

$$f(\overrightarrow{r_1}, \overrightarrow{r_2}, \overrightarrow{v_1}, \overrightarrow{v_2}) = (\overrightarrow{r_2} - \overrightarrow{r_1}) \cdot (\overrightarrow{v_2} - \overrightarrow{v_1}) = 0$$
  
$$\dot{f} > 0$$

where:

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- $\overrightarrow{r_1}, \overrightarrow{v_1}$  are the position and velocity vectors of the primary satellite in inertial frame
- $\overrightarrow{r_2}, \overrightarrow{v_2}$  are the position and velocity vectors of the secondary satellite/object in inertial frame

The collinearity entry and exit events are defined mathematically as the epoch when:

$$\gamma - \gamma_0 = acos\left(\frac{\overrightarrow{r_1} \cdot \overrightarrow{r_2}}{|\overrightarrow{r_1}| \cdot |\overrightarrow{r_2}|}\right) = 0$$

 $\dot{\gamma} > 0$  for collinearity exit event  $\dot{\gamma} < 0$  for collinearity entry event

- JCollinearity •
  - detects collinearities

(from stations; for RF

interferences)

where:

- γ is the angular separation (collinearity angle) between the primary satellite and the secondary satellite/object as seen from a given ground station
- γ<sub>0</sub> is the user-defined collinearity angle





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# Conclusions



#### **EUMETSAT and Orekit: Summary**

- · Orekit is used for a wide variety of applications at EUMETSAT,
  - stand-alone apps, also relatively complex
  - also integrated with Python and/or Matlab [main operational Flight Dynamics or related Data Processing chains rely however on other s/w packages]

=> future evolutions may well consider Orekit

- Our experience: It allows rapid development of powerful and reliable applications, as well as quick analyses (also for the non-Java expert when for example integrated into Matlab)
  - For cases where accuracy or integrity is necessary, results need cross-validation with other independent s/w (as usual)

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### **Orekit and EUMETSAT**



#### **Questions?**

